



Name : .....

Roll No. : .....

Invigilator's Signature : .....

**CS/M.Tech(ECE/VLSI)/SEM-2/MVLSI-201/2012  
2012**

**PROCESSOR ARCHITECTURE FOR VLSI DESIGN**

Time Allotted : 3 Hours

Full Marks : 70

*The figures in the margin indicate full marks.*

*Candidates are required to give their answers in their own words  
as far as practicable.*

Answer any seven questions.

7 × 10 = 70

1. What do you understand by pipelining ? 2

Define the following terms : 4 × 2

- i) Pipe-stage
- ii) Pipeline machine cycle
- iii) Latency
- iv) Throughput of a pipeline.

2. Define 3 types of pipelining hazards. What could be the  
easiest common solution ? ( 3 × 3 ) + 1

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3. y-instructions X---stage : calculate the speed up when pipeline used.

Define the term "interlocking & forwarding".

State the difference between temporal & spatial parallelism.

$$4 + 2 + 2 + 2$$

4. State the difference between static & dynamic branch prediction.

Describe the difference between control flow and data flow model.

Describe the difference between super-scalar and VLIW model.

Describe the difference between Static & Dynamic data flow architecture.

What is the difference between dual core & dual processor CPU ?

$$5 \times 2$$

5. What is scoreboard implementation ? Show the implementation of the following example :

mul Reg1, Reg3, Reg5

sub Reg2, Reg4, Reg3

div Reg2, Reg1, Reg4

add Reg6, Reg2, Reg3.



6. State the Flynn's Classical Taxonomy. Define the advantages & disadvantages of shared & distributed memory. State with example a parallelizable problem & a non-parallelizable problem.

7. Calculate total % of lines saved :

i) Max Instructions/Line : 5

Add R1 R1R1

Add R1 R1R1

Add R1 R1R1

Add R1 R1R1

Add R1 R1R1

ii) Max instructions/Line : 3

Add R1 R2 R3

Add R4 R5 R6

Add R7 R8 R9

Add R10 R2 R3

Add R1 R1R1

iii) Max instructions/Line : 2

Add R1 R2 R3

Add R4 R5 R6

Add R7 R8 R9

Add R10 R2 R3

Add R1 R1R1

What do you mean by EPIC hardware ? State the advantages of EPIC hardware over general VLIW architecture ?

2 + 2 + 2 + 2 + 2



8. Draw the architecture for PIC 16F877A. State the advantages of PIC micro-controllers over the 8051 micro-controllers. Name one of the compilers used for PIC.

State how the PWM is obtained in PIC 16F877A. 3 + 3 + 4

9. What do you mean by re-configurable computing ? Define "on the fly re-configurability". What do you understand by IP-cores or customized soft CPU ? How the co-processors and accelerators facilitate the speed-up operation ? What is test bench ? Why do you perform the behavioural simulation ?

1 + 1 + 2 + 3 + 1 + 2

