	Utech
Name:	
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Inviailator's Sianature :	

## CS/M.Tech (ME)/SEM-2/ME-1203-III(E-02)/2010 2010

## MANUFACTURING AUTOMATION

Time Allotted: 3 Hours Full Marks: 70

The figures in the margin indicate full marks.

Candidates are required to give their answers in their own words as far as practicable.

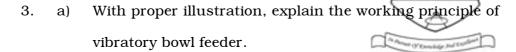
Answer any *five* question.  $5 \times 14 = 70$ 

- 1. a) How are the transfer systems classified into different categories depending on the Assembly machines?
  - b) With suitable sketch, state the difference between continuous transfer and intermittent transfer.
  - c) With suitable example, explain the working principle of a Pawl type transfer system. 4 + 5 + 5
- 2. a) Cite the factors affecting the choice of indexing mechanism for an assembly machine.
  - b) Prove that for a Geneva disc, ratio of Active time & idle time = (Z-2)/(Z+2), where Z is the number of slots in the disk.
  - c) With detailed sketch, differentiate between the ratchet and pawl type of indexing mechanism with cross cam indexing unit. 4+4+6

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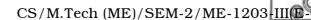


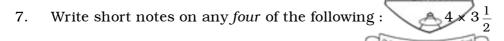
- b) Deduce the expression for navigation of small through vibratory bowl feeder in term of normal track acceleration and acceleration due to gravity. 6+8
- 4. a) What are the commonly used feeders used in feeding of the small components?
  - b) For a reciprocating tupe hopper, how is the hopper wall inclination expressed in terms of coefficient of frication?

6 + 8

- 5. a) With suitable illustration, explain how the screw like components are delivered to the delivery chute through a fork hopper.
  - b) What is a hook hopper feeder? Elaborate the detailed procedure for design of the Hook. 6 + (2 + 6)
- 6. What is meant by orienting device? Explain at least five types of orienting devices with suitable illustration.

$$2 + (4 \times 3)$$





- a) Orienting system
- b) Feed tracks
- c) Escapement mechanism
- d) Downtime in assembly machine
- e) Rules for product design for automated assembly.