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Invigilator's Signature :	

CS/B.TECH(IT)/SEM-7/IT-703A/2012-13 2012 COMPUTER GRAPHICS

Time Allotted: 3 Hours Full Marks: 70

The figures in the margin indicate full marks.

Candidates are required to give their answers in their own words as far as practicable.

GROUP - A

(Multiple Choice Type Questions)

1. Choose the correct alternatives from the following:

 $10 \times 1 = 10$

- i) Which of the following is/are true ragarding vector devices or raster devices?
 - a) Vector devices position the input/output mechanism by scanning the whole input/output area.
 - b) Raster devices scan the whole input/output area row by row moving from top to bottom to produce the input/output.
 - c) A raster display device uses rectangular arrays of dots (pixels) to display an image.
 - d) Examples of raster devices are Plotter and Plasma Display.

7302 Turn over

CS/B.TECH(IT)/SEM-7/IT-703A/2012-13



- ii) Which of the following is not a modern application for Computer Graphics ?
 - a) Scientific Visualization
 - b) Computer Aided Geometric Design
 - c) Video Games
 - d) Stop-motion animation
 - e) Geographical Information Systems.
- iii) Which of the following affine transforms does not affect vectors?
 - a) Translation
- b) Scale
- c) Rotation
- d) Shear
- e) Reflection.
- iv) Which of the following affine transforms is not used in rotation around a specific axis and point?
 - a) Translation
- b) Scale
- c) Rotation
- d) Shear
- e) Reflection.
- v) Homogeneous form of the point (9, 6, 3, 3) is
 - a) (1, 2, 3)
- b) (3, 2, 1)
- c) (3, 2, 1, 1)
- d) (9, 6, 3)
- e) (9, 6, 3, 1).
- vi) With the DDA (Digital Differential analyzer) algorithm, what will be the amount added to the secondary component each time through the loop (incrementing value ?
 - a) $\frac{-1}{2}$

b) $\frac{3}{4}$

c) $\frac{1}{2}$

d) $\frac{-4}{3}$

- a) frame buffer
- b) RAM

c) ROM

- d) Cache Memory.
- viii) Consider the two points A(1, 1) and B(4, 7).

Let P(u) = (x(u), y(u)) be a parametric line function.

What is a parametric equation of the line segment joining the points A and B?

- a) x(u) = 3u, y(u) = u + 1
- b) x(u) = 3u + 1, y(u) = 6u + 1
- c) x(u) = 4u, y(u) = 7u
- d) x(u) = u, y(u) = 2u + 1.
- ix) What are the window to viewport mappings for W = (0, 100, 50, 200) and V = (10, 50, 0, 60)?
 - a) sx = 0.4 x + 10 and sy = 0.4y 20
 - b) sx = 0.4 x + 10 and sy = 0.4y + 20
 - c) sx = 0.4 x 10 and sy = 0.4y 20
 - d) sx = 0.4 x + 20 and sy = 0.4y 20
 - e) sx = 0.4 x + 20 and sy = 0.4y 10
- x) If you rotate the point (20, 30) by 90 degrees anticlockwise and then translate it by (-20, 0) and then scale it by (2, 1), where will the point be ?
 - a) (100, -20)
- b) (100, 10)
- c) (-100, 20)
- d) (100, 20).

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(Short Answer Type Questions)

Answer any three of the following.

 $3 \times 5 = 15$

- 2. What is the difference between raster scan and random scan?
- 3. What is aspect ratio? Define persistence.

2 + 3

- 4. Write down DDA algorithm.
- 5. State the drawback of mid-point circle drawing algorithm.

GROUP - C

(Long Answer Type Questions)

Answer any *three* of the following. $3 \times 15 = 45$

- 6. a) Write the homogeneous co-ordinate transformation matrices for the basic transformation.
 - b) Given the final transformation matrix that scales the given triangle (A (2, 2), B (4, 2), C (4, 4)) twice to its size about point A.
 - c) Explain the conceptual model of the 3D viewing process. 5 + 5 + 5
- 7. a) Discuss DDA line drawing algorithm. Highlighted advantage and disadvantage of this algorithm.
 - b) Indicate which pixel positions would be chosen by DDA algorithm when scan converting a line from pixel coordinate (1, 2) to pixel coordinate (7, 9).

(7+3)+5

- 8. a) Explain mid-value sub-division line clipping.
 - b) State the inequities for line and point clipping.
 - c) Explain Flood fill and Boundary fill algorithm. 5 + 4 + 6
- 9. Write short notes on any *three* of the following :

 3×5

- a) Polygon Fill Algorithm
- b) Clipping (2 D)
- c) 3D parallel Projection
- d) Scan line Algorithm
- e) Color Model.

7302 4