



Name : .....

Roll No. : .....

Invigilator's Signature : .....

**CS/B.TECH (ICE)/SEM-6/IC-601/2012**  
**2012**  
**PROCESS CONTROL**

Time Allotted : 3 Hours

Full Marks : 70

*The figures in the margin indicate full marks.*

*Candidates are required to give their answers in their own words  
as far as practicable.*

**GROUP – A**  
**( Multiple Choice Type Questions )**

1. Choose the correct alternatives for any *ten* of the following :

$10 \times 1 = 10$

- i) The function of reset action in process control is to
  - a) reduce rise time
  - b) reduce steady state error
  - c) reduce oscillation in the response
  - d) increase the overall gain.
- ii) Butterfly valve is
  - a) sliding stem type
  - b) movable stem type
  - c) both sliding and movable type
  - d) none of these.



iii) The offset current and offset voltage of an ideal op-amp are

- a) 0, 0
- b) 20 nA and 2mV
- c)  $\infty$ ,  $\infty$
- d) 20 mA and 2 mV.

iv) In a flapper-nozzle mechanism, if flapper moves closer to the nozzle, the nozzle back pressure will

- a) decrease
- b) increase
- c) remain constant
- d) depend upon the construction.

v) Rangeability is defined by

- a)  $\frac{Q_{\max}}{Q_{\min}}$
- b)  $\frac{\Delta P_{\max}}{\Delta P_{\min}}$
- c)  $\frac{C_{V_{\max}}}{C_{V_{\min}}}$
- d)  $\frac{\Delta P_{\max}}{\Delta Q_{\max}}$ .

vi) Which of the following is not a part of the final control element ?

- a) Actuator
- b) Controller
- c) Control valve
- d) All of these.



- vii) In pneumatic system, electrical capacitance is analogous to
- a) resistance to flow      b) volume of air
  - c) filled helical tube      d) none of these.
- viii) For satisfactory control of gas pressure, the control action should be
- a) ON-OFF control mode
  - b) proportional control mode
  - c) integral control mode
  - d) PID control mode.
- ix) Cohen-Coon's tuning rule is used for
- a) open loop system
  - b) closed loop system
  - c) both open and closed loop system
  - d) none of these.

- GROUP – B**

Answer any *three* of the following.  $3 \times 5 = 15$

- 4



3. What is integral time constant ? Prove that proportional band  $= \frac{100}{K_c}$ , where the symbol has usual meaning. 2 + 3

4. A PI controller indicates an output of 12 mA when the error is zero. The set point is suddenly increased to 14mA and the controller output is recorded and given below :

Time $t$ , sec	0	10	20	30
Output, mA	14	16	18	20

Find  $K_P$  and  $T_i$ .

5. With a neat diagram explain the operating principle of a pneumatic proportional controller.
6. How can you practically determine the installed valve characteristic of a control valve in an installation ? Give the reasons for determining the installed characteristic.

### GROUP – C

#### ( Long Answer Type Questions )

Answer any *three* of the following. 3 × 15 = 45

7. a) Describe the importance of three well known time integral performance criteria, ISE, IAE and ITAE. How can you choose the most appropriate criterion for a particular operation ? 5



- b) What are the situations under which an ON/OFF controller would provide satisfactory performance ? 5
- c) Design a PI controller with proportional band of 30% and an integration time of 10 sec. The 4-20 mA input converts into 0-2V error signal. The output is to be in between 0 and 10 V. 5
8. a) In the context of time delay system schemes, explain in detail how Smith's controller can be employed. 7
- b) What are self-regulating and non-self-regulating processes ? Explain each of them with one example. 5
- c) Differentiate between "log" and "delay". 3
9. a) Define turn-down of a control valve. Explain the cavitations and flashing phenomena of a control valve with the help of diagram. 5
- b) Differentiate between erosion and corrosion phenomena in control valves. What are the advantages and disadvantages of a double-seated control valve ? 2 + 3
- c) A heating furnace requires a control valve passing 10 gpm preheated light fuel oil ( $S_g = 0.5$ ) at full load and only 0.2 gpm at the smallest load. The pressure differential at wide open is 20 psi. Calculate (a)  $C_V$ ; (b)  $K_V$ . 5



10. a) What are composite control modes ? Name three composite control modes. 4
- b) Explain in detail how can ultimate cycle method be employed for controller tuning. 5
- c) How does Schmitt trigger help in reducing the effect of noise on switching in a process control system ? 4
- d) What is "degree of freedom" of process ? 2
11. Write short notes on any *three* on the following : 3 × 5
- a) Pneumatic relay
- b) Electronic error detector
- c) Feed forward control
- d) Valve positioner
- e) Electro-pneumatic converter.
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