	Utech
Name :	
Roll No.:	A Grant of Knowledge Stad Explana
Invigilator's Signature :	

# **ELECTRICAL MACHINES - II**

Time Allotted: 3 Hours Full Marks: 70

The figures in the margin indicate full marks.

Candidates are required to give their answers in their own words as far as practicable.

#### GROUP - A

# ( Multiple Choice Type Questions )

1. Choose the correct alternatives for any ten of the following:

 $10 \times 1 = 10$ 

- i) A 3-phase slip-ring induction motor has 4-pole stator and 2-pole rotor. With its stator energised from 50 Hz source, the rotor would run at a no-load speed of
  - a) somewhat less than 1500 rpm
  - b) somewhat less than 3000 rpm
  - c) somewhat less than 1000 rpm
  - d) of zero rpm.

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- ii) A voltmeter gives 120 oscillations per minute when connected to the rotor of a 3-phase induction motor.The stator frequency is 50 Hz. The slip of the motor is
  - a) 2%

b) 2.5%

c) 4%

- d) 5%.
- iii) The ratio of starting torque to rated torque for a 3-phase induction motor with star-delta starter is
  - a)  $\frac{1}{3}$

b) 3

c)  $\frac{1}{\sqrt{3}}$ 

- d)  $\sqrt{3}$  .
- iv) Crawling in 3-phase induction motor occurs at a rotor speed equal to
  - a)  $\frac{1}{3}$  of synchronous speed
  - b)  $\frac{1}{5}$  of synchrons speed
  - c)  $\frac{1}{7}$  of synchronous speed
  - d)  $\frac{1}{11}$  of synchronous speed.
- v) In double cage induction motor, the starting torque is mainly produced by
  - a) inner cage
  - b) outer cage
  - c) both cages
  - d) slit portion between the two cages.

- vi) The effect of leading power factor on the voltage regulation of an alternator is
  - a) decreasing in nature
  - b) increasing in nature
  - c) decreasing or increasing
  - d) inconsequential.
- vii) The magnetic circuit of 3-phase alternator at unity pf is
  - a) underexcited
- b) overexcited
- c) normally excited
- d) none of these.
- viii) In a 3-phase salient pole synchronous machine where  $x_d=d$ -raxis synchronous reactance and  $x_q=q$ -axis synchronous reactance
  - a)  $x_d = x_q$
- b)  $x_d < x_q$
- c)  $x_d > x_q$
- d)  $x_q = 0$ .
- ix) The direction of rotation of a 1-phase induction motor can be reversed by
  - a) reversing the leads of supply
  - b) reversing the leads of main winding only
  - c) reversing the leads of auxiliary winding only
  - d) either (b) or (c).

- x) A 6-pole, 50 Hz, single phase induction motor runs at a speed of 900 rpm. The frequencies of the current in the cage rotor will be
  - a) 5 Hz, 55 Hz
- b) 5 Hz, 75 Hz
- c) 5 Hz, 95 Hz
- d) 10 Hz, 95 Hz.
- xi) Rotational voltage in ac commutator motor is
  - a) in phase with exciting field
  - b) out of phase with exciting field
  - c) either (a) or (b)
  - d) none of these.

#### GROUP - B

## (Short Answer Type Questions)

Answer any *three* of the following.

 $3 \times 5 = 15$ 

- 2. a) What is a circle diagram? What assumptions are made in drawing the circle diagram?
  - b) Why is reduced stator voltage applied to perform the blocked rotor test of 3-phase induction motor?

(1+2)+2

- 3. How do the change in supply voltage and frequency affect induction motor performance?  $2\frac{1}{2} + 2\frac{1}{2}$
- 4. 3-phase synchronous motors are not self starting. Explain. How this problem can be overcome? 4+1
- 5. What will happen when a dc shunt motor is operated from a single phase ac supply of same nominal voltage?
- 6. Explain why in single phase induction motor, the direction of rotation is always from auxiliary winding to main winding whether a resistance or capacitance is connected in series with auxiliary winding.

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### **GROUP - C**

## (Long Answer Type Questions)

Answer any *three* of the following.  $3 \times 15 = 45$ 

- 7. a) A single phase induction motor has no starting torque but running torque. Explain from double revolving field theory.
  - b) A 220 V, 50 Hz, single phase induction motor has rotational loss of 15 W and the following parameters are given:

 $r_1 = 2.5$  ohm,  $x_1 = 5.5$  ohm,  $x_m = 98$  ohm,  $r_2 = 6.5$  ohm,  $x_2 = 4.3$  ohm.

Find the input current, shaft output and efficiency at 4% slip. 6 + (4 + 3 + 2)

- 8. a) Why does synchronous impedance method is known as pessimistic method of computation of voltage regulation?
  - b) Two reaction theory is applied only to salient pole machines. Explain.
  - c) A 3.3 kV, 3-phase, star connected alternator has a full-load current of 100 A. Under short circuit condition it takes 5A field current to produce full load current. The *emf* on open circuit for the same excitation is 900 V (L-L). The armature resistance is 0.9 ohm/ph. Determine regulation for 0.8 pf lagging and 0.8 pf leading conditions. 3+4+8

- 9. a) Derive an expression for torque in 3-phase induction motor.
  - b) What will happen to the speed of a 3-phase slip-ring induction motor when (i) in phase slip frequency voltage, (ii) out-off phase slip frequency voltage are injected into rotor circuit?
  - c) A 3-phase, 4-pole, 10 kW, 400 V delta connected machine gives the following test results :

No-load test: 400 V, 8 A, 250 W

Blocked Rotor test: 90 V, 35 A, 1350 W

The dc resistance of the stator winding per phase measured immediately after the blocked rotor test is 0.6 ohm. Calculate the rotational loss and equivalent circuit parameters. 3 + 4 + (2 + 6)

- 10. a) What is a universal motor? Explain how it develops torque.
  - b) Draw the phasor diagram of an uncompensated *ac* series motor and show that it operates at a higher speed on *dc* supply than on *ac* supply for same supply voltage and load current.
  - c) How the use of compensating winding improves motor performance. (1+3)+(4+4)+3

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11. Write short notes on any *three* of the following :

- a) Speed control of 3-phase induction motor
- b) Cross field theory of single phase induction motor
- c) Variable Reluctance Stepper Motor
- d) Armature reactance in alternator
- e) Permanent magnet machines
- f) Classification of single phase induction motor.

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