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CS/B.TECH(BME)/SEM-6/BME-602/2012 2012 BIOMEDICAL SIGNAL PROCESSING

Time Allotted: 3 Hours Full Marks: 70

The figures in the margin indicate full marks.

Candidates are required to give their answers in their own words as far as practicable.

GROUP – A

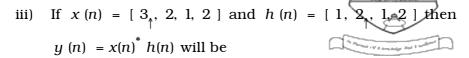
(Multiple Choice Type Questions)

 $1. \quad \hbox{Choose the correct alternatives for the following}:$

 $10 \times 1 = 10$

- i) Z transform of a time domain signal helps in predicting...... of the system through which the signal is passing.
 - a) convergency
- b) divergency
- c) stability
- d) accuracy.
- ii) The angle of the poles with respect to the +ve real axis of z-plane provides of the sinusoidal signal.
 - a) amplitude
- b) phase
- c) frequency
- d) PSD.

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- $[3, 8_{\uparrow}, 8, 13, 9, 9, 4]$ b) $[3, 8_{\uparrow}, 8, 12, 9, 4, 4]$
- $[3_{\uparrow}, 8, 8, 12, 9, 4, 4]$ d) $[3, 8, 8, 13_{\uparrow}, 9, 9, 4]$ c)
- Z-transform of step function u(n) is
 - 1/(z + 1)a)
- b) 1/(z-1)
- c) z / (z + 1)
- d) z / (z 1).
- v) DFT of each point needs complex multiplications and complex additions.
 - N + 1 and N
- b) N and N-1
- c)
- N^2 and N(N-1) d) N-1 and N^2 .
- Which of the following systems is non-causal? vi)
 - y(n) = 2x(n+1)a)
 - y(n) = 3x(n) + 5x(n-1)b)
 - c) y(n) = x(n)
 - y(n) = 4x(n) + 3x(n-1) + 99x(n-2). d)
- $X(Z) = Z\{x(n)\},$ then $Z\{a^nx(n)\} = ?;$ where vii) If a^n = exponential function.
 - X(a z)a)

- b) $X(a^{-1}z)$
- $X(a z^{-1})$ c)
- d) $X(a^{-1}z^{-1})$.



- viii) Poles in the LHS of s-plane are plotted in of z-plane.
 - a) Inside the unit circle b) On the unit circle
 - c) Outside the unit circle d) None of these.
- ix) A Signal is an Energy signal if
 - a) Power is 0, Energy is 0
 - b) Power is 0, Energy is non-zero finite
 - c) Power is non-zero finite, Energy is ∞
 - d) Power is ∞ , Energy is ∞ .
- x) The impulse response of FIR filters are computed for
 - a) finite number of samples
 - b) infinite number of samples
 - c) depending on the values of H(z)
 - d) both (a) and (c).

GROUP - B

(Short Answer Type Questions)

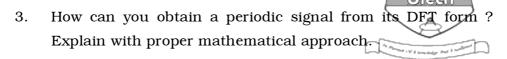
Answer any *three* of the following.

 $3 \times 5 = 15$

2. Find the Convolution Integral of the following two signals:

$$x_1(t) = \cos \pi t \ [u \ (t+1) - u \ (t-3)], \ x_2(t) = u(t)$$

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4. Find out the *Z*-transform and ROC of the following:

$$x(n) = a^n u(n) + b^n u(-n-1)$$
, where $b < a$

5. Find the DIF-FFT of the following data sequence :

$$x(n) = \{ 1, 2, 3, 4, 5, 6, 7, 8 \}$$

6. Determine he Direct Form II of the following system:

$$y(n) + 2y(n-1) + 3y(n-2) = 3x(n) + 5x(n-1) + x(n-2)$$

7. Determine order and the poles of a type I Low Pass Chebyshev filter that has a 1 dB ripple in the pass band, a cut-off frequency $\Omega_P = 1000\Pi$, a stop band frequency of 2000Π , and an attenuation of 40 dB or more for $\Omega \ge \Omega_S$.

GROUP - C

(Long Answer Type Questions)

Answer any *three* of the following. $3 \times 15 = 45$

8. Find the complete solution of the following difference equation :

$$y(n) - 3/4y(n-1) + 1/8y(n-2) = 2\sin(n\pi/2)$$
, where

$$y(-1) = 2$$
, $y(-2) = 4$.

Find the IDFT of $X(K) = \{ 3, 2 + j, 1, 2 - j \}$ 9 + 6

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- 9. a) 2 Poles of a function of LT1 system are on the ROC at 2 points P1 and P2 making angle ω_0 with the positive real axis in z-plane at both 1st and 4th quadrant respectively, of a unit circle of radius r. 2 zeros are located at origin and at the point of intersection 2 poles are making with the positive real axis. Obtain the corresponding time domain signal.
 - b) Determine the z-transform of the signal

$$x(n) = [3 (2^n) - 4(3^n)] u(n)$$

c) Determine the inverse z-transform of

$$X(z) = \frac{1}{1 - 1 \cdot 5z^{-1} + 0 \cdot 5z^{-2}}$$

when (i) ROC : |z| > 1,

(ii)
$$ROC: |Z| < 0.5$$

10. Find out the Inverse Z-transform of

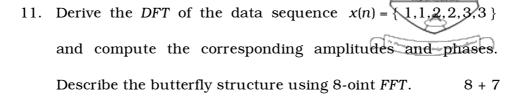
 $X(Z) = z(z^2 - 4z + 5)/\{z-1)(z-2)(z-3)\}$ for the following conditions

- a) 2 < |z| < 3
- b) |z| < 1
- c) |z| > 3.

Compute the convolution of the following two sequences:

$$x(n) = \{1, 1, 0_{\uparrow}, 1, 0, 1\}; h(n) = \{1, 2, 1, 1_{\uparrow}, 2, 1\}$$
 9 + 6

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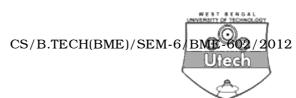
- 12. a) A system is defined by the following difference equation $y(n) 2ky(n-1) + k^2y(n-2) = x(n)$
 - (i) Determine the range of parameter k for which the system is stable.
 - (ii) Determine the transfer function h(n) of the system.
 - (iii) Draw the *ROC*.
 - b) Convert the analog filter with system function

$$H_a(s) = \frac{s + 0 \cdot 2}{(s + 0 \cdot 2)^2 + 9}$$

into a digital IIR filter by means of the bilinear transformation. The digital filter have T=0.1.

c) Determine the order and poles of a LP Butterworth filter that has a -3 dB BW of 5000 Hz and an attenuation of 40 dB at 1000 Hz.

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- 13. Write short note on any three of the following
 - a) Short Time Fourier Transform (STFT) and Wavelet
 - b) Sampling Theorem and Aliasing Effect
 - c) Radix 2 Transform
 - d) Proof of the Associative property with a block diagram
 - e) Recursive and Non-Recursive Filters
 - f) Significance of Fast Fourier Transform (FFT).

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